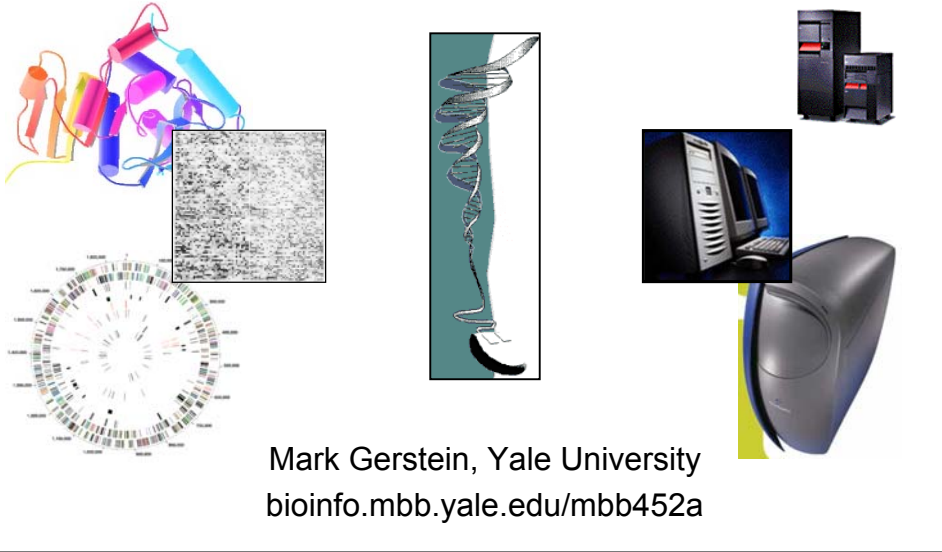


BIOINFORMATICS

Structures

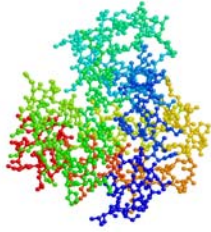


Mark Gerstein, Yale University
bioinfo.mbb.yale.edu/mbb452a

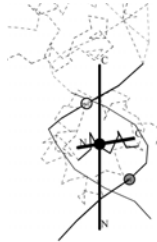
Contents: Structures

- What Structures Look Like?
- Structural Alignment by Iterated Dynamic Programming
 - ◊ RMS Superposition
 - ◊ Rotating and Translating Structures
- Scoring Structural Similarity
- Other Aspects of Structural Alignment
 - ◊ Distance Matrix based methods
- Elaborating structures
 - ◊ Surfaces and volumes

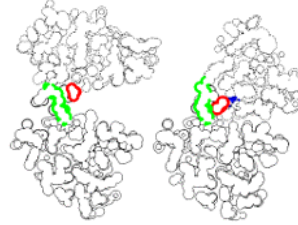
Other Aspects of Structure, Besides just Comparing Atom Positions



Atom
Position,
XYZ triplets



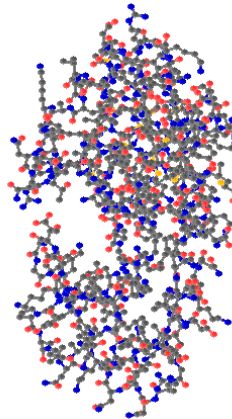
Lines, Axes,
Angles



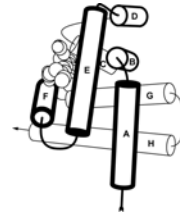
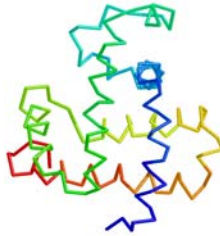
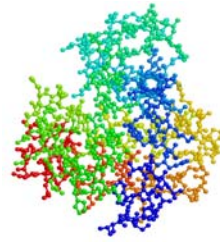
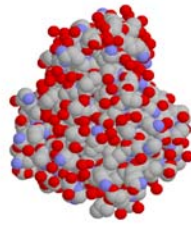
Surfaces, Volumes

What is Protein Geometry?

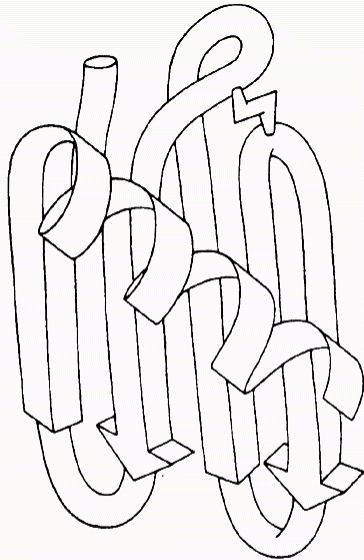
- Coordinates (X, Y, Z's)
- Derivative Concepts
 - ◇ Distance, Surface Area, Volume, Cavity, Groove, Axes, Angle, &c
- Relation to
 - ◇ Function, Energies (E(x)), Dynamics (dx/dt)



Depicting
Protein
Structure:
Sperm
Whale
Myoglobin



7 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu



Incredulase

Incredulase

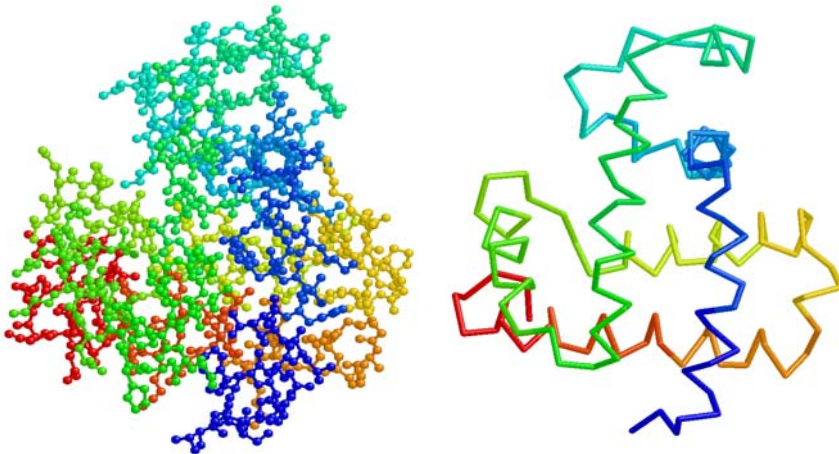
J.S. Richardson and D.C. Richardson, "Some design principles: Betabellin", in D.L. Oxender and C.F. Fox (Eds.), "Protein Engineering", Alan R. Liss, 1987, p. 149-163

8 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Structure alignment - Method

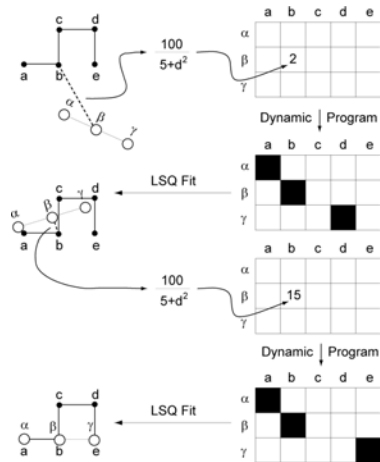
- What Structures Look Like?
- Structural Alignment by Iterated Dynamic Programming
 - ◊ RMS Superposition
- Scoring Structural Similarity
- Other Aspects of Structural Alignment
 - ◊ Distance Matrix based methods
 - ◊ Fold Library
- Relation of Sequence Similarity to Structural and Functional Similarity
- Protein Geometry
- Surface I (Calculation)
- Calculation of Volume
- Voronoi Volumes & Packing
- Standard Volumes & Radii
- Surfaces II (Relationship to Volumes)
- Other Applications of Volumes -- Motions, Docking

Sperm Whale Myoglobin



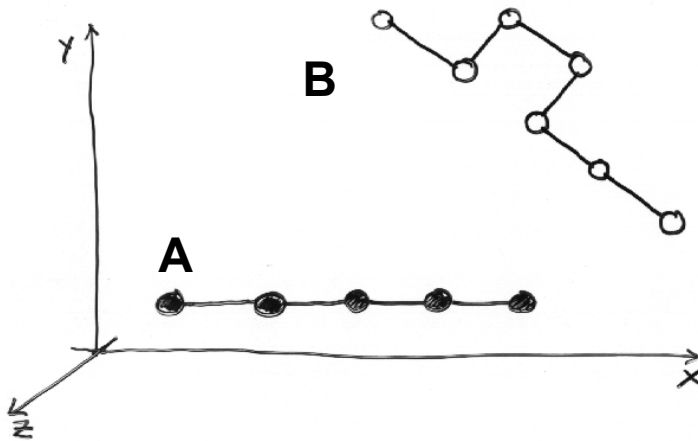
Automatically Comparing Protein Structures

- Given 2 Structures (A & B), 2 Basic Comparison Operations
 - 1 Given an alignment optimally **SUPERIMPOSE** A onto B
Find Best R & T to move A onto B
 - 2 **Find an Alignment** between A and B based on their 3D coordinates



Core

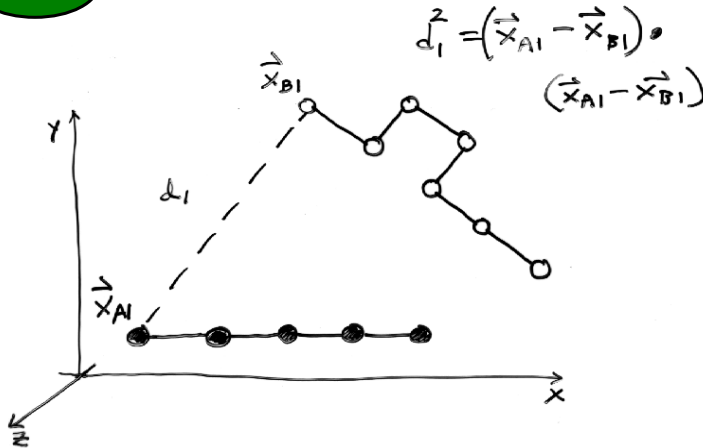
RMS Superposition (1)



Core

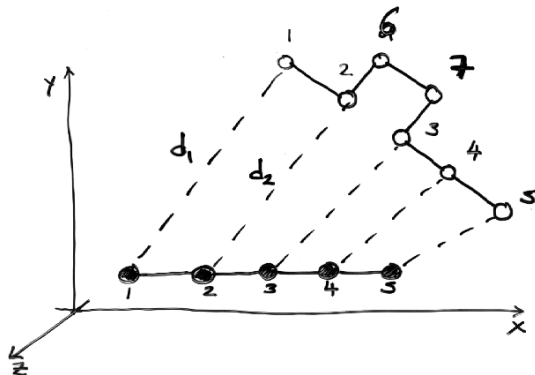
RMS Superposition (2): Distance Between an Atom in 2 Structures

Core



RMS Superposition (3): RMS Distance Between Aligned Atoms in 2 Structures

$$RMS = \sqrt{\frac{\sum_{i=1}^5 (\vec{x}_{Ai} - \vec{x}_{Bi})^2}{5}} \sim \frac{d_1 + d_2 + d_3 + d_4 + d_5}{5}$$



Core

RMS Superposition (4): Rigid-Body Rotation and Translation of One Structure (B)

$\vec{x}'_{Bi} = R(\theta) \vec{x}_{Bi} + \vec{T}$
ROTATE & TRANSLATE

6 parameters

$\vec{T} = (T_x, T_y, T_z) \quad R(\theta, \phi, \psi)$

Core

RMS Superposition (5): Optimal Movement of One Structure to Minimize the RMS

Core

Methods of
Solution:

springs
($F \sim kx$)

SVD

Kabsch

$RMS = \sqrt{\frac{1}{N} \sum_i (\vec{x}_{Ai} - \vec{x}'_{Bi})^2} = \sqrt{\frac{1}{N} \sum_i (\vec{x}_{Ai} - R(\theta) \vec{x}_{Bi} - \vec{T})^2}$

Change 6 parameters to minimize RMS

θ, ϕ, ψ

6

T_x, T_y, T_z

Rotation Matrices

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$
 ROTATION MATRIX

2D

AROUND z

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

3D

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Computer Graphics Systems: Rotation, Translation, and XY Projection

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \xrightarrow{\text{ROT MAT}} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \xrightarrow{\text{PROJ}} \begin{pmatrix} x \\ y \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

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$x_i = \begin{pmatrix} x_i \\ y_i \\ z_i \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 2 \end{pmatrix} = \vec{x}$
 TRANSLATE (UP BY 2)
 $\vec{x} + \vec{T} = \begin{pmatrix} 3 \\ 3 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 4 \end{pmatrix}$
 MOST ABSTRACT
 $R \vec{x}_i = \vec{x}_i'$
 $\begin{pmatrix} a & b & c \\ d & e & f \\ s & h & i \end{pmatrix} \rightarrow \begin{pmatrix} \frac{3\sqrt{3}}{2} - \frac{3}{2} \\ \frac{3}{2} + \frac{3\sqrt{3}}{2} \\ 2 \end{pmatrix}$
 θ, ϕ, ψ ROT BY 30° AROUND z
 PRACTICAL ABSTRACT
 $\begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$
 $\begin{pmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} & 0 \\ \frac{1}{2} & \frac{\sqrt{3}}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ 3 \\ 2 \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{2} \\ \frac{3}{2} \\ 2 \end{pmatrix} \leftarrow \text{OX VECTOR}$

Worked Example of Rigid Body Movement

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End of class 2002,11.11

(Bioinfo-9)

[starting in sequences handout]

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Alignment (1) Make a Similarity Matrix (Like Dot Plot)

	A	B	C	N	Y	R	Q	C	L	C	R	P	M
A	1												
Y					1								
C			1					1	1				
Y					1								
N				1									
R						1					1		
C			1					1	1				
K													
C			1					1	1				
R						1					1		
B		1											
P												1	

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Structural Alignment (1b) Make a Similarity Matrix (Generalized Similarity Matrix)

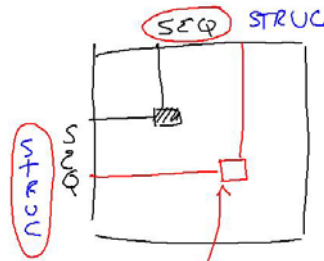
- $PAM(A,V) = 0.5$
 - ◊ Applies at every position
- $S(aa @ i, aa @ J)$
 - ◊ Specific Matrix for each pair of residues
 - i in protein 1 and J in protein 2**
 - ◊ Example is Y near N-term. matches any C-term. residue (Y at J=2)
- $S(i,J)$
 - ◊ Doesn't need to depend on a.a. identities at all!
 - ◊ Just need to make up a score for matching residue i in protein 1 with residue J in protein 2

		1	2	3	4	5	6	7	8	9	10	11	12	13
	A	1												
1	A	1												
2	Y				1			5	5	5	5	5	5	5
3	C			1				1	1					
4	Y				1									
5	N				1									
6	R					1					1			
7	C			1				1	1					
8	K													
9	C			1				1	1					
10	R					1					1			
11	B		1											
12	P												1	

J ↓

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Seq. Alignment, Struc. Alignment, Threading



\mathbb{P} = SEQ IDENTITY FOR SEQ ALIGNMENT
 = STRUC COORD SIM. FOR STRUC ALIGNMENT
 = MATCH OF SEQ TO 3D STRUC FOR THREADING

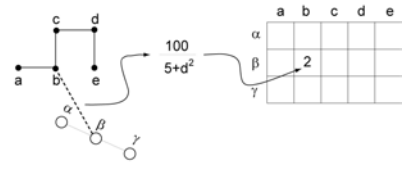
Core

Structural Alignment (1c*) Similarity Matrix for Structural Alignment

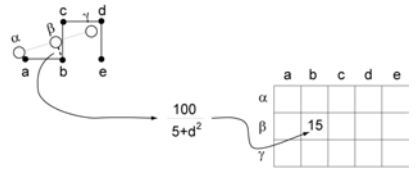
- Structural Alignment
 - ◇ Similarity Matrix $S(i,j)$ depends on the 3D coordinates of residues i and j
 - ◇ Distance between CA of i and j

$$d = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2 + (z_i - z_j)^2}$$

$$M(i,j) = 100 / (5 + d^2)$$



- Threading
 - ◇ $S(i,j)$ depends on the how well the amino acid at position i in protein 1 fits into the 3D structural environment at position j of protein 2



Alignment (2): Dynamic Programming, Start Computing the Sum Matrix

```

new_value_cell(R,C) <=
  cell(R,C) { Old value, either 1 or 0 }
  + Max[
    cell (R+1, C+1), { Diagonally Down, no gaps }
    cells(R+1, C+2 to C_max), { Down a row, making col. gap }
    cells(R+2 to R_max, C+2) { Down a col., making row gap }
  ]
  
```

	A	B	C	N	Y	R	Q	C	L	C	R	P	M
A	1												
Y				1									
C			1					1	1				
Y					1								
N						1							
R							1				1		
C			1					1	1				
K													
C			1					1	1				
R						1					1		
B		1											
P												1	

	A	B	C	N	Y	R	Q	C	L	C	R	P	M
A	1												
Y				1									
C			1					1	1				
Y					1								
N						1							
R							1				1		
C			1					1	1				
K													
C			1					1	1				
R						1					2	0	0
B	1	2	1	1	1	1	1	1	1	1	1	0	0
P	0	0	0	0	0	0	0	0	0	0	0	1	0

Alignment (3): Dynamic Programming, Keep Going

	A	B	C	N	Y	R	Q	C	L	C	R	P	M
A	1												
Y				1									
C			1					1	1				
Y					1								
N						1							
R							1				1		
C			1					1	1				
K													
C			1					1	1				
R						1					2	0	0
B	1	2	1	1	1	1	1	1	1	1	1	0	0
P	0	0	0	0	0	0	0	0	0	0	0	1	0

	A	B	C	N	Y	R	Q	C	L	C	R	P	M	
A	1													
Y				1										
C			1					1	1					
Y					1									
N						1								
R							5	4	3	3	2	2	0	0
C	3	3	4	3	3	3	3	4	3	3	1	0	0	
K	3	3	3	3	3	3	3	3	3	2	1	0	0	
C	2	2	3	2	2	2	2	3	2	3	1	0	0	
R	2	1	1	1	1	2	1	1	1	1	2	0	0	
B	1	2	1	1	1	1	1	1	1	1	1	0	0	
P	0	0	0	0	0	0	0	0	0	0	0	1	0	

Alignment (4): Dynamic Programming, Sum Matrix All Done

	A	B	C	N	Y	R	Q	C	L	C	R	P	M
A	1												
Y					1								
C			1					1	1				
Y					1								
N				1									
R						5	4	3	3	2	2	0	0
C	3	3	4	3	3	3	3	4	3	3	1	0	0
K	3	3	3	3	3	3	3	3	3	2	1	0	0
C	2	2	3	2	2	2	2	3	2	3	1	0	0
R	2	1	1	1	1	2	1	1	1	1	2	0	0
B	1	2	1	1	1	1	1	1	1	1	1	0	0
P	0	0	0	0	0	0	0	0	0	0	0	1	0

	A	B	C	N	Y	R	Q	C	L	C	R	P	M
A	8	7	6	6	5	4	4	3	3	2	1	0	0
Y	7	7	6	6	6	4	4	3	3	2	1	0	0
C	6	6	7	6	5	4	4	4	3	3	1	0	0
Y	6	6	6	5	6	4	4	3	3	2	1	0	0
N	5	5	5	6	5	4	4	3	3	2	1	0	0
R	4	4	4	4	4	5	4	3	3	2	2	0	0
C	3	3	4	3	3	3	3	4	3	3	1	0	0
K	3	3	3	3	3	3	3	3	3	2	1	0	0
C	2	2	3	2	2	2	2	3	2	3	1	0	0
R	2	1	1	1	1	2	1	1	1	1	2	0	0
B	1	2	1	1	1	1	1	1	1	1	1	0	0
P	0	0	0	0	0	0	0	0	0	0	0	1	0

Alignment (5): Traceback

Find Best Score (8) and Trace Back

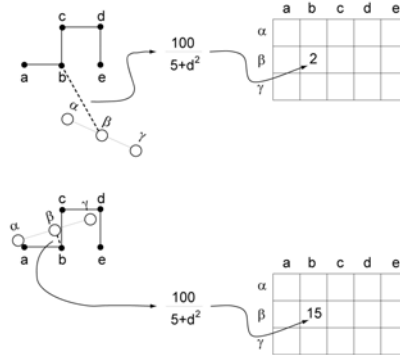
A B C N Y - R Q C L C R - P M

A Y C - Y N R - C K C R B P

	A	B	C	N	Y	R	Q	C	L	C	R	P	M
A	8	7	6	6	5	4	4	3	3	2	1	0	0
Y	7	7	6	6	6	4	4	3	3	2	1	0	0
C	6	6	7	6	5	4	4	4	3	3	1	0	0
Y	6	6	6	5	6	4	4	3	3	2	1	0	0
N	5	5	5	6	5	4	4	3	3	2	1	0	0
R	4	4	4	4	4	5	4	3	3	2	2	0	0
C	3	3	4	3	3	3	3	4	3	3	1	0	0
K	3	3	3	3	3	3	3	3	3	2	1	0	0
C	2	2	3	2	2	2	2	3	2	3	1	0	0
R	2	1	1	1	1	2	1	1	1	1	2	0	0
B	1	2	1	1	1	1	1	1	1	1	1	0	0
P	0	0	0	0	0	0	0	0	0	0	0	1	0

In Structural Alignment, Not Yet Done (Step 6*)

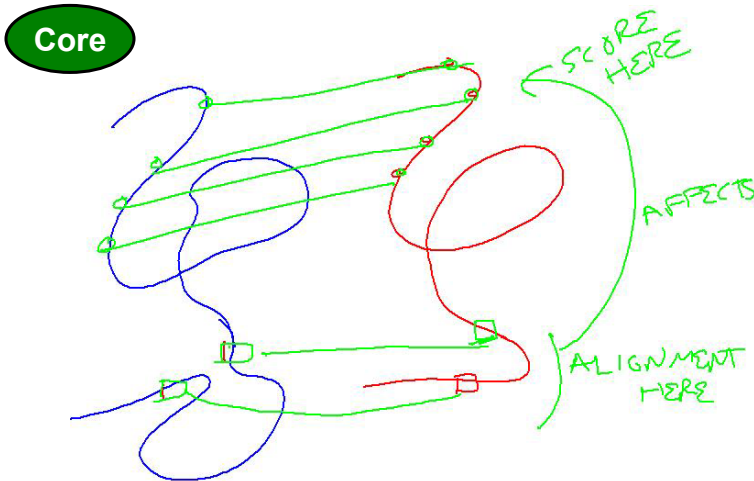
- Use Alignment to LSQ Fit Structure B onto Structure A
 - ◊ However, movement of B will now change the Similarity Matrix
- This Violates Fundamental Premise of Dynamic Programming
 - ◊ Way Residue at i is aligned can now affect previously optimal alignment of residues (from 1 to $i-1$)



```

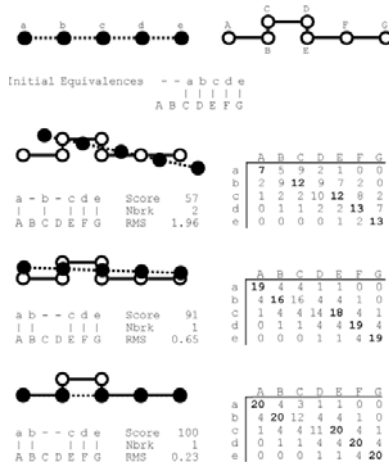
ACSQRP--LRV-SH -R SENCV
A-SNKPQLVKLMTH VK DFCV-
    
```

How central idea of dynamic programming is violated in structural alignment



Structural Alignment (7*), Iterate Until Convergence

- 1 Compute Sim. Matrix
- 2 Align via Dyn. Prog.
- 3 RMS Fit Based on Alignment
- 4 Move Structure B
- 5 Re-compute Sim. Matrix
- 6 If changed from #1, GOTO #2



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Structure alignment - Scoring

- What Structures Look Like?
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- Standard Volumes & Radii
- Surfaces II (Relationship to Volumes)
- Other Applications of Volumes -- Motions, Docking

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Score S at End Just Like SW Score, but also have final RMS

S = Total Score

S(i,j) = similarity matrix score for aligning i and j

Sum is carried out over all aligned i and j

n = number of gaps (assuming no gap ext. penalty)

G = gap penalty

$$S = \sum_{i,j} S(i,j) - nG$$

Some Similarities are Readily Apparent others are more Subtle

Easy:
Globins

125 res.,
~1.5 Å



Tricky:
Ig C & V

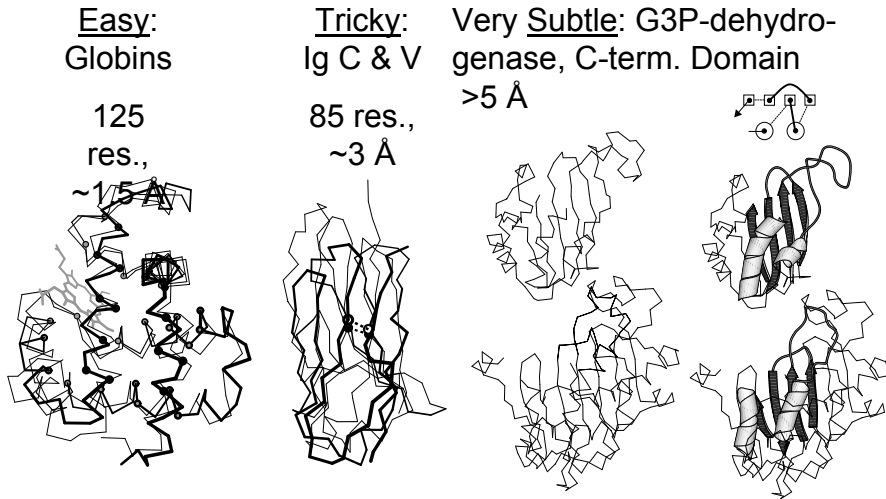
85 res.,
~3 Å



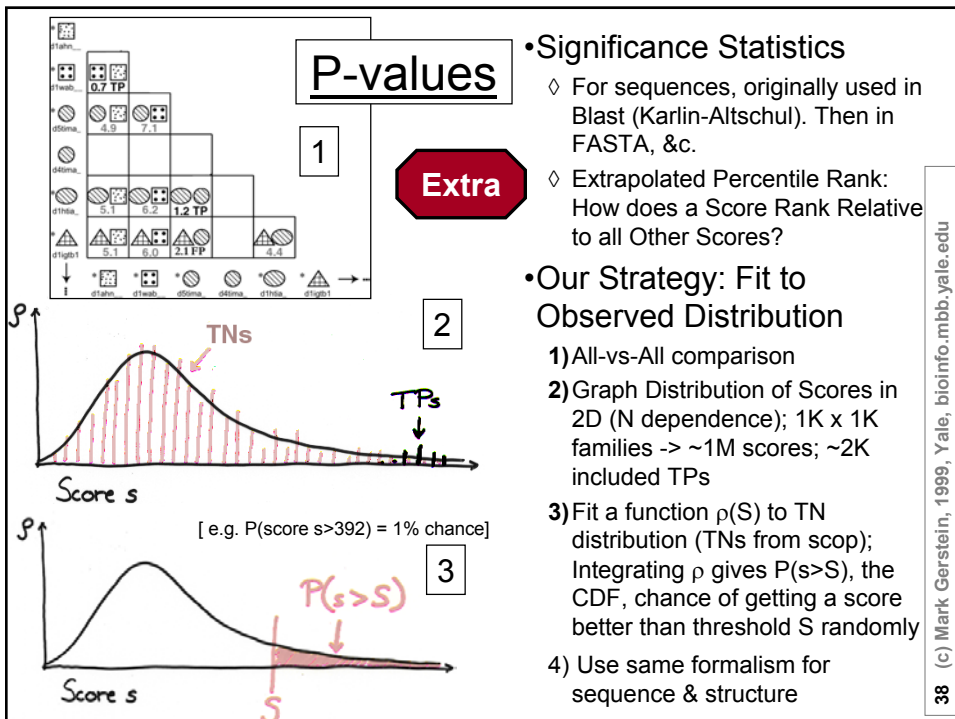
Very Subtle: G3P-dehydrogenase, C-term. Domain
>5 Å



Some Similarities are Readily Apparent others are more Subtle



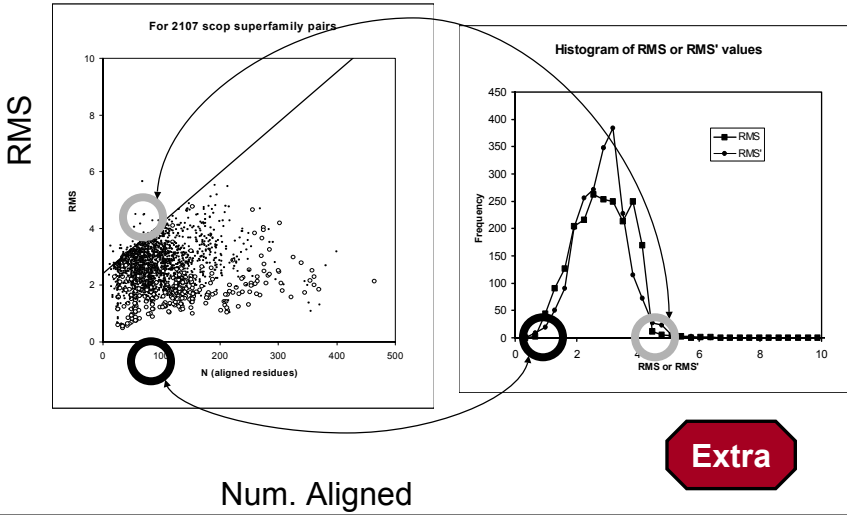
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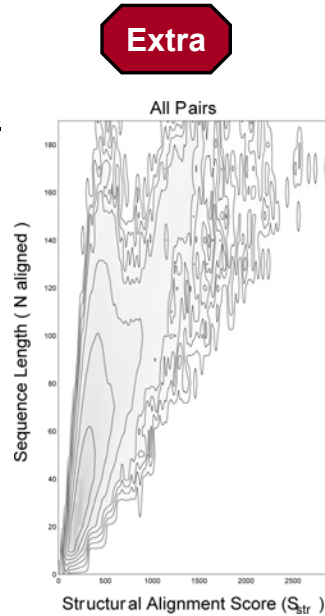
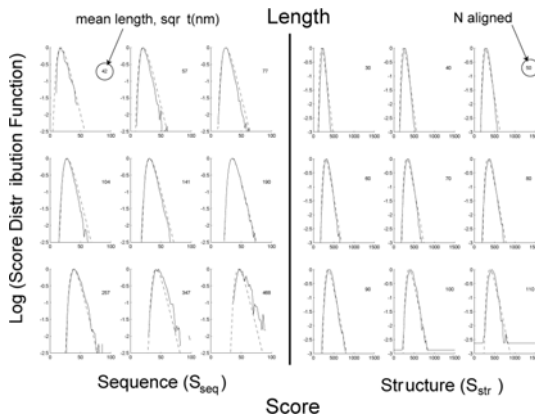
38 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Statistics on Range of Similarities

For 2107 pairs, only 2% Outliers (with subtle similarity)



Scores from Structural Alignment Distributed Just Like Ones from Sequence Alignment (E.V.D.)



Same Results for Sequence & Structure

3 Free Parm. fit to EVD involving: **a, b, σ**.
These are the only difference betw. sequence
and structure.

$$Z = \frac{S - (a \ln N + b)}{\sigma}$$

$$S = \sum_{i,j} M(i, j) - G$$

$$\rho(z) = \exp(-z - e^{-z})$$

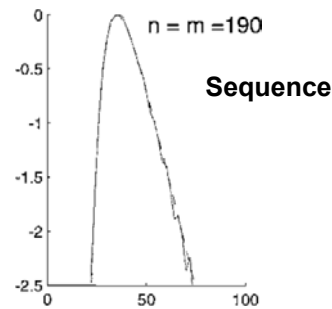
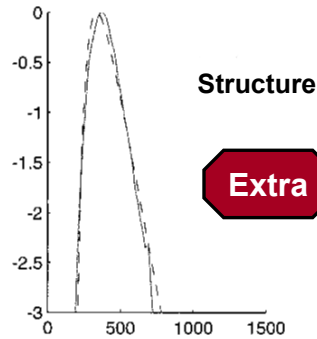
N, G, M also defined differently for sequence
and structure.

N = number of residues matched.

G = total gap penalty.

M(i,j) = similarity matrix

(Blossum for seq. or $M_{str}(i,j)$, struc.)



Score Significance (P-value) derived from Extreme Value Distribution (just like BLAST, FASTA)

F(s) = E.V.D of scores

$$F(s) = \exp(-Z(s) - \exp(-Z(s)))$$

$$Z(s) = As + \ln(N) + B$$

s = Score from random alignment

N length of sequence matched

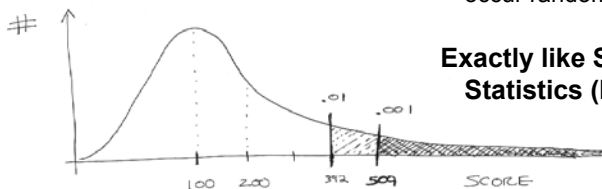
A & B are fit parameters

$$P(s > S) = \text{CDF} = \text{integral}[F(s)]$$

$$P(s > S) = 1 - \exp(-\exp(-Z(s)))$$

Given Score S (1%), P (s > S) is
the chance that a given random
score **s** is greater than the
threshold

i.e. P-value gives chance score would
occur randomly



**Exactly like Sequence Matching
Statistics (BLAST and FASTA)**

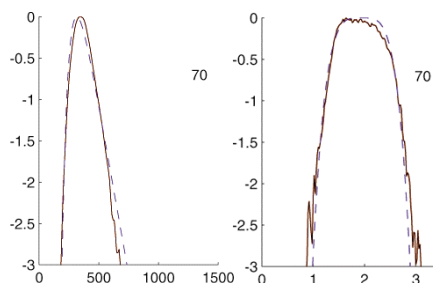
Extra

RMS is a similarity Score

Extra

- Also, RMS doesn't work instead of structural alignment (no EVD fit)
 - ◊ RMS penalizes worst fitting atoms, easily skewed

$$S_{\text{str}} \quad \text{RMS}$$
$$\sum \frac{100}{5 + \mathbf{d}_i^2} \text{ vs } \sqrt{\sum \mathbf{d}_i^2}$$



43 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

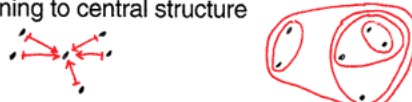
Structure alignment - Other methods

- What Structures Look Like?
- Structural Alignment by Iterated Dynamic Programming
 - ◊ RMS Superposition
- Scoring Structural Similarity
- Other Aspects of Structural Alignment
 - ◊ Distance Matrix based methods
 - ◊ Fold Library
- Relation of Sequence Similarity to Structural and Functional Similarity
- Protein Geometry
- Surface I (Calculation)
- Calculation of Volume
- Voronoi Volumes & Packing
- Standard Volumes & Radii
- Surfaces II (Relationship to Volumes)
- Other Applications of Volumes -- Motions, Docking

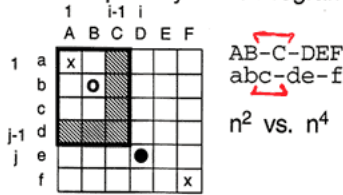
44 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Refine Method

- Multiple Alignment by aligning to central structure



- More Complex Dynamic Programming

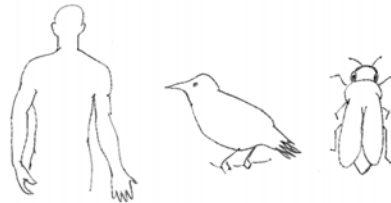


Extra

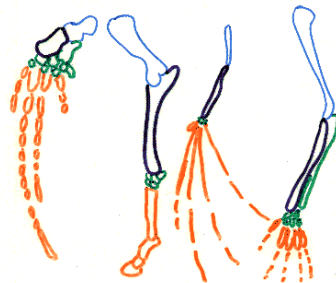
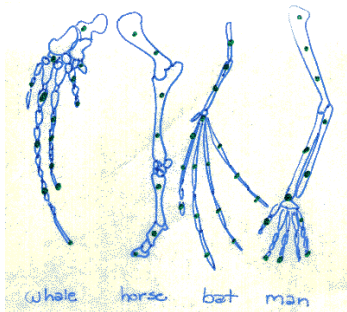
- Find "best" aligned regions
 - "Core-finding" to remove outliers
 - "Noisy" suboptimal paths

	A	y	B	C	D	E
A	2	0	0	0	0	0
B	0	2	3	1	1	1
C	0	1	2	5	2	2
x	0	1	1	2	5	4
D	0	1	1	2	6	5
E	0	1	1	2	4	8

Significance Ignoring Crucial Features in Structural Similarity



Extra



Other Methods of Structural Alignment

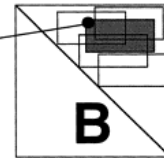
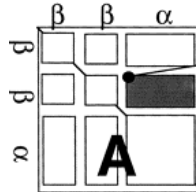
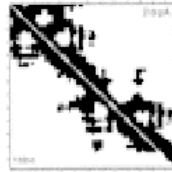
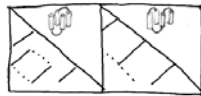
- RMS fitting used universally, but other alignment methods
- Comparison of Distance Matrices

- ◊ Holm & Sander, DALI
- ◊ Taylor & Orengo

Other Methods

Rossmann
Taylor
Sander-x3 } dist. matr.
Barton }
Blundell } dist. matr, prop. match.

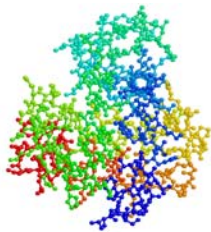
Cohen - soap bubble
Artymiuk
Isgras } similar subgraph



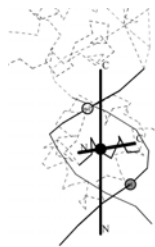
Structure Hashing
Bryant, VAST
Rice, Artymiuk

Others
Cohen (Soap)
Sippl
Godzik (Lattice)

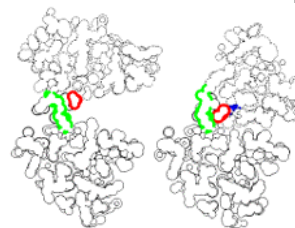
Other Aspects of Structure, Besides just Comparing Atom Positions



Atom
Position,
XYZ triplets



Lines, Axes,
Angles



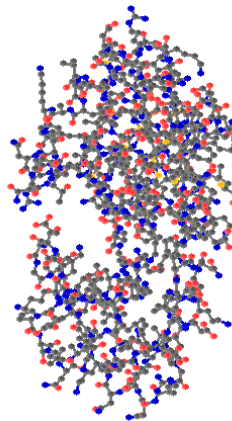
Surfaces, Volumes



**From here to end
of Structures all is
“extra” unless
otherwise marked.**

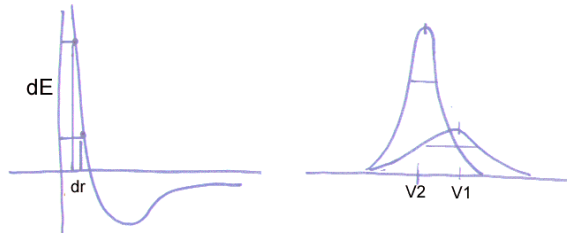
What is Protein Geometry?

- Coordinates (X, Y, Z's)
- Derivative Concepts
 - ◇ Distance, Surface Area, Volume, Cavity, Groove, Axes, Angle, &c
- Relation to
 - ◇ Function, Energies (E(x)), Dynamics (dx/dt)



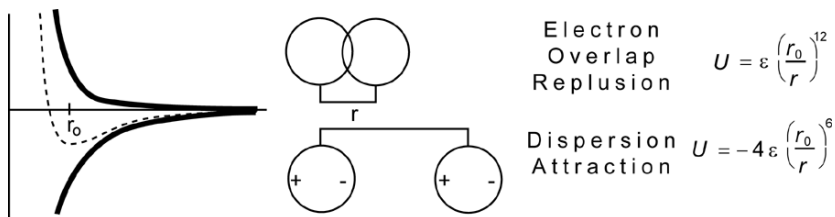
Small Packing Changes Significant

- Exponential dependence
- Bounded within a range of 0.5 (.8 and .3)
- Many observations in standard volumes gives small error about the mean (SD/sqrt(N))



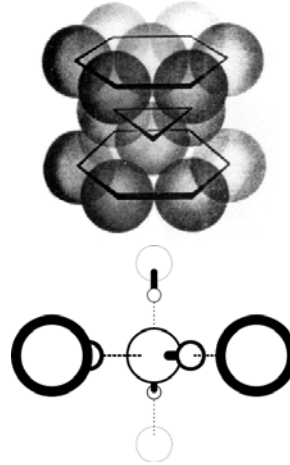
Packing ~ VDW force

- Longer-range isotropic attractive tail provides general cohesion
- Shorter-ranged repulsion determines detailed geometry of interaction
- Billiard Ball model, WCA Theory



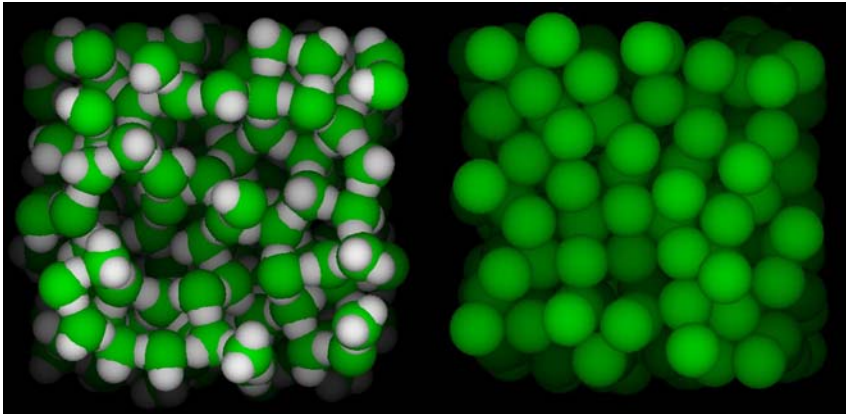
Close-packing is Default

- No tight packing when highly directional interactions (such as H-bonds) need to be satisfied
- Packing spheres (.74), hexagonal
- Water (~.35), "Open" tetrahedral, H-bonds



53 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Water v. Argon



More Complex Systems -- what to do?

54 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Close-Packing of Spheres

- Efficiency
 - ◊ Volume Spheres / Volume of space
- Close packed spheres
 - ◊ 74% volume filled
 - ◊ Coordination of 12
 - ◊ Two Ways of laying out
- FCC
 - ◊ cubic close packing
 - ◊ ABC layers
- hcp
 - ◊ Hexagonally close packed
 - ◊ ABABAB

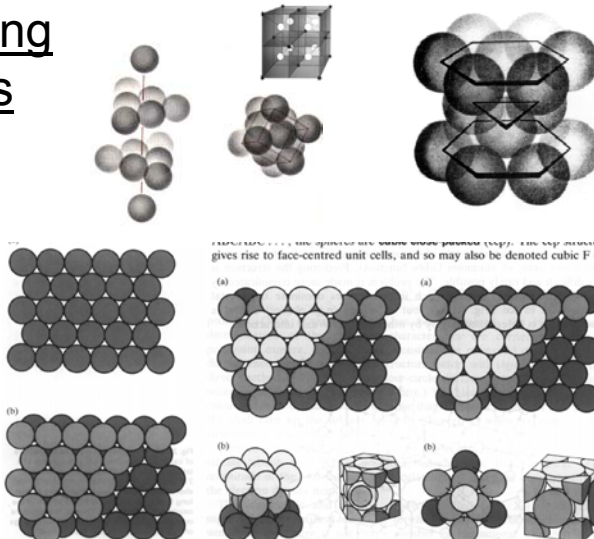


Fig. 21.20 The close-packing of identical spheres. (a) The first layer of close-packed spheres. (b) The second layer of close-packed spheres occupies the dips of the first layer. The two layers are the AB component of the structure.

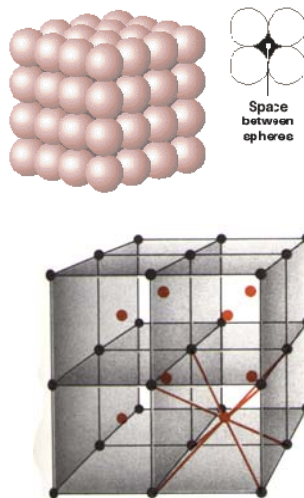
Fig. 21.21 The third layer of close-packed spheres might occupy the dips lying directly above the spheres in the first layer, resulting in an ABA structure (a) which corresponds to hexagonal close-packing (b). This hcp structure is possessed by the elements Be, Cd, Co, Hg, Mg, Ti, and Zn.

Fig. 21.22 Alternatively, the third layer might lie in the dips that are not above the spheres in the first layer, resulting in an ABC structure (a) which corresponds to cubic close-packing (b). This ccp (or fcc) structure is possessed by the elements Ag, Al, Ar, Au, Ca, Cu, Ni, Pt, and Xe.

Illustration Credits: Atkins, Pchem, 634

Other Well Known Sphere Arrangements

- Simple cubic packing
 - ◊ 8 nbrs
 - ◊ 52% efficiency
- bcc cubic packing
 - ◊ one sphere sits in middle of 8 others (body-centered)
 - ◊ 8 nbrs
 - ◊ 68% efficiency
- fcc -> bcc -> simple
 - ◊ apx 3/4, 2/3, 1/2

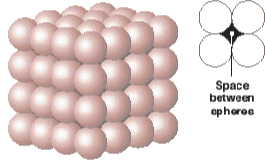


Optimal Packing Finally Proved

After Four Centuries, an Answer

What's the best way to stack a bunch of round objects? The answer, whether they are cannonballs or oranges, seems to be an extension of the familiar pyramid-shaped stack seen in grocery stores everywhere.

SIMPLE CUBIC LATTICE

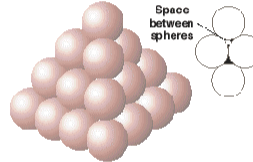


STACKING EFFICIENCY **52%**

In this arrangement, the spheres sit directly on top of one another, leaving a space between the spheres that is almost equal to the sphere itself.

Stacking efficiency = volume of the spheres / (volume of the spheres + the space between the spheres)

FACE-CENTERED CUBIC LATTICE

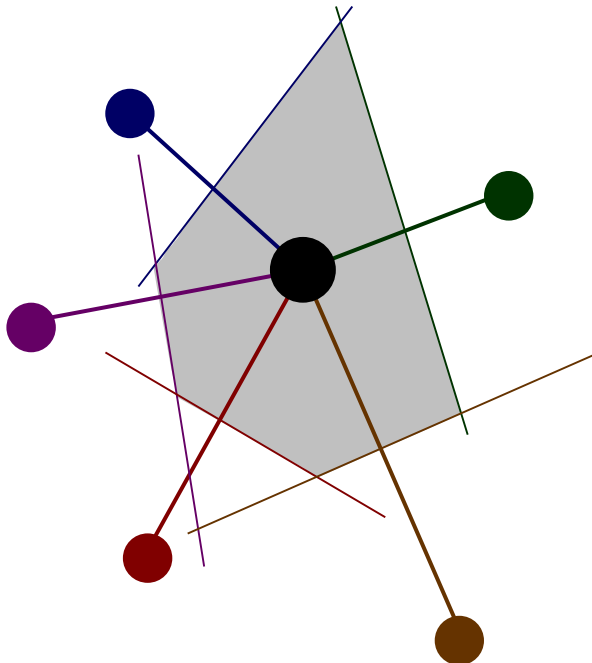


STACKING EFFICIENCY **74%**

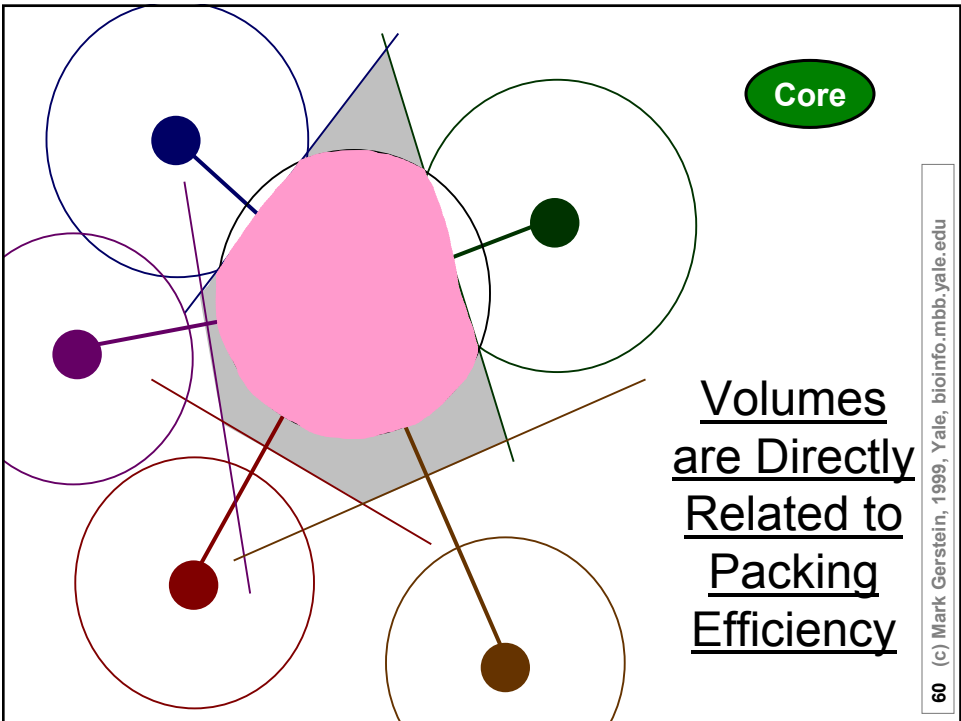
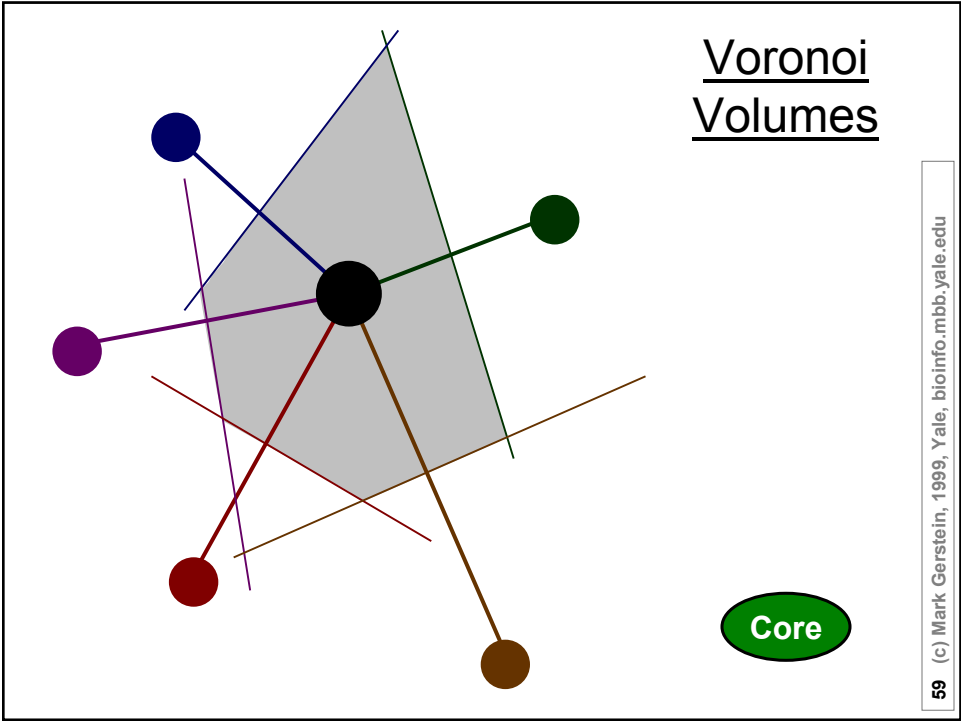
In this more efficient arrangement, the spheres sit off-center, resting within the pocket created by the spheres sitting side-by-side below.

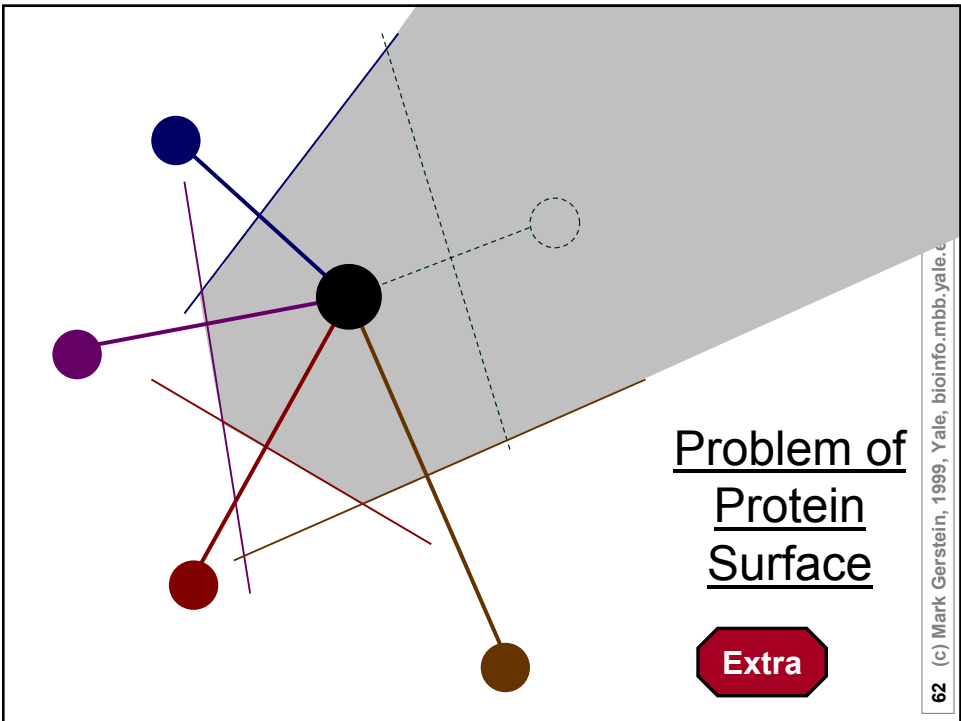
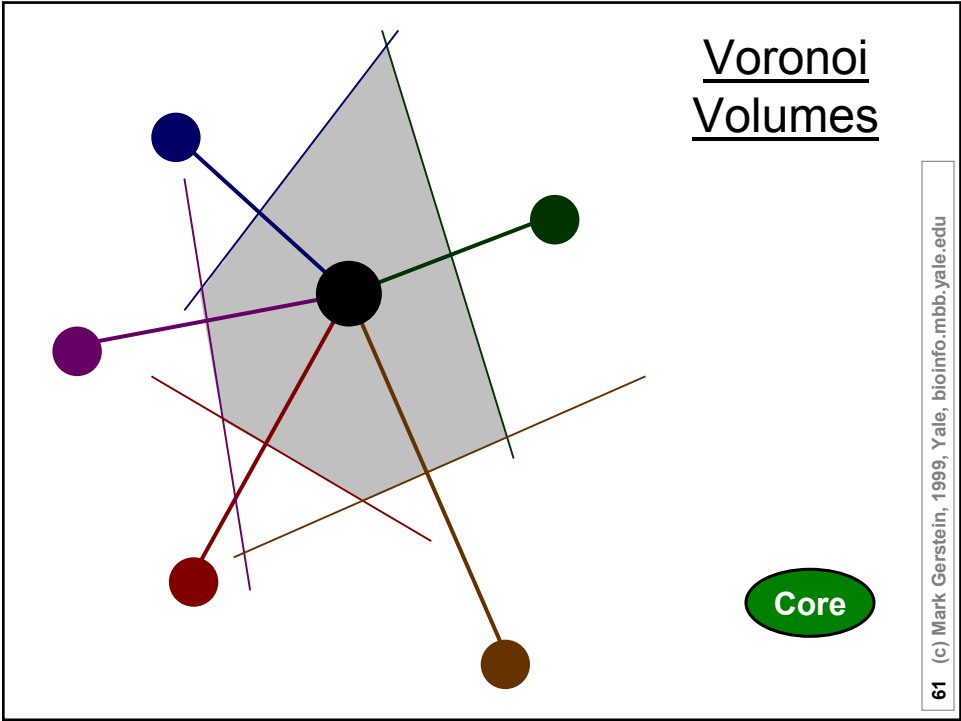
Illustration Credits: Singh, New York Times

Voronoi Volumes



Core





Voronoi
Volumes

Extra

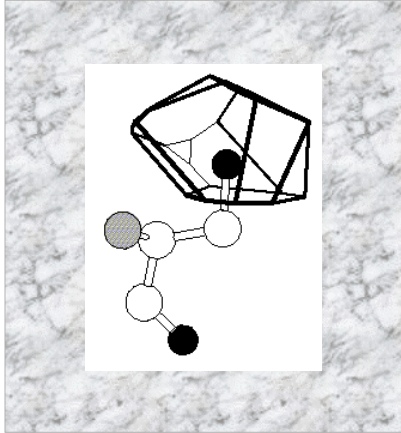
63 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Missing
Atoms Give
Looser
Packing

Extra

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Finding Voronoi Volumes



- Draw Lines in Between Atoms
- Draw Equidistant Planes Between Atoms
- Intersect Planes for a Volume

Classic Papers

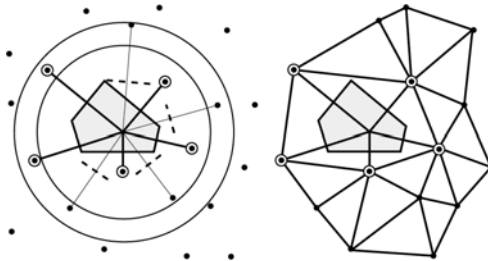
- Lee, B. & Richards, F. M. (1971). "The Interpretation of Protein Structures: Estimation of Static Accessibility," *J. Mol. Biol.* **55**, 379-400.
- Richards, F. M. (1974). "The Interpretation of Protein Structures: Total Volume, Group Volume Distributions and Packing Density," *J. Mol. Biol.* **82**, 1-14.
- Richards, F. M. (1977). "Areas, Volumes, Packing, and Protein Structure," *Ann. Rev. Biophys. Bioeng.* **6**, 151-76.

Properties of Voronoi Polyhedra

- If Voronoi polyhedra are constructed around atoms in a periodic system, such as in a crystal, all the volume in the unit cell will be apportioned to the atoms. There will be no gaps or cavities as there would be if one, for instance, simply drew spheres around the atoms.
- Voronoi volume of an atom is a weighted average of distances to all its neighbors, where the weighting factor is the contact area with the neighbor.

Delaunay Triangulation, the Natural Way to Define Packing Neighbors

- Related to Voronoi polyhedra (dual)
- What “coordination number” does an atom have?
Doesn't depend on distance
- alpha shape
- threading

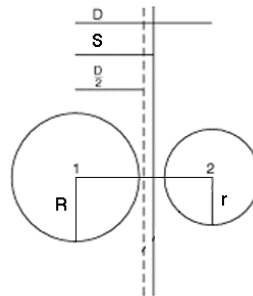


Voronoi diagrams are generally useful, beyond proteins

- Border of D.T. is Convex Hull
- D.T. produces "fatest" possible triangles which makes it convenient for things such as finite element analysis.
- Nearest neighbor problems. The nearest neighbor of a query point in center of the Voronoi diagram in which it resides
- Largest empty circle in a collection of points has center at a Voronoi vertex
- Voronoi volume of "something" often is a useful weighting factor. This fact can be used, for instance, to weight sequences in alignment to correct for over or under-representation

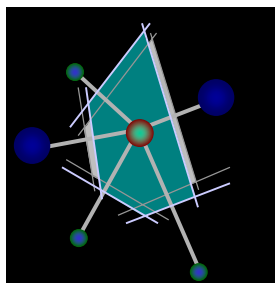
Atoms have different sizes

- Difficulty with Voronoi Meth.
Not all atoms created equal
- Solutions
 - ◇ Bisection -- plane midway between atoms
 - ◇ Method B (Richards)
Positions the dividing plane according to ratio
 - ◇ Radical Plane
- VDW Radii Set



Why Type the Atoms?

- Calculate Average Volumes
- Compare to Protein Atoms of Similar Type
- Allows for Modified Voronoi Volumes: Instead of Equidistant Planes, Use the Ratio of Their Radius



Courtesy of N Voss

Set of VDW Radii

- Great differences in a sensitive parameter (Radii for carbon 1.87 vs 2.00)
- Complex calculation: minimizing SD, iterative procedure, from protein structures
- Look for common distances in CCD
- Preliminary Solution

Atom	Bondi	New
C4	1.87	1.88
C3H1	1.76	1.76
C3H0	1.76	1.61
O1H0	1.40	1.42
O2H1	1.40	1.46
N	1.65	1.64
S	1.85	1.77

Different Sets of Radii

Atom Type & Symbol	Bondi 1968	Lee & Richards 1971	Strake & Rupley 1973	Richards 1974	Chothia 1975	Rich- mond & Richards 1978	Gelin & Karpus 1979	Dunfield et al. 1979	ENCAD derived 1995	ChRAM derived 1995	Tsai et al. 1998
-CH ₃	2.00	1.80	2.00	2.00	1.87	1.90	1.95	2.13	1.82	1.88	1.88
-CH ₂ -	2.00	1.80	2.00	2.00	1.87	1.90	1.90	2.23	1.82	1.88	1.88
>CH-	-	1.70	2.00	2.00	1.87	1.90	1.85	2.38	1.82	1.88	1.88
=CH	-	1.80	1.85	*	1.76	1.70	1.90	2.10	1.74	1.80	1.76
>C=	1.74	1.80	*	1.70	1.76	1.70	1.80	1.85	1.74	1.80	1.61
-NH ₃ ⁺	-	1.80	1.50	2.00	1.50	0.70	1.75	-	1.68	1.40	1.64
-NH ₂	1.75	1.80	1.50	-	1.65	1.70	1.70	-	1.68	1.40	1.64
>NH	1.65	1.52	1.40	1.70	1.65	1.70	1.65	1.75	1.68	1.40	1.64
=O	1.50	1.80	1.40	1.40	1.40	1.40	1.60	1.56	1.34	1.38	1.42
-OH	-	1.80	1.40	1.60	1.40	1.40	1.70	-	1.54	1.53	1.46
-OM	-	1.80	1.89	1.50	1.40	1.40	1.60	1.62	1.34	1.41	1.42
-SH	-	1.80	1.85	-	1.85	1.80	1.90	-	1.82	1.56	1.77
-S-	1.80	-	-	1.80	1.85	1.80	1.90	2.08	1.82	1.56	1.77

73 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Voronoi Volumes, the Natural Way to Measure Packing

Packing Efficiency

$$= \frac{\text{Volume-of-Object}}{\text{Space-it-occupies}}$$

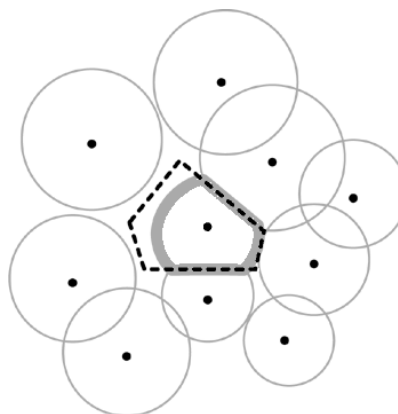
$$= \frac{V(\text{VDW})}{V(\text{Voronoi})}$$

- Absolute v relative eff.

$$V1 / V2$$

- Other methods

- ◊ Measure Cavity Volume
(grids, constructions, &c)



74 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Standard Residue Volumes

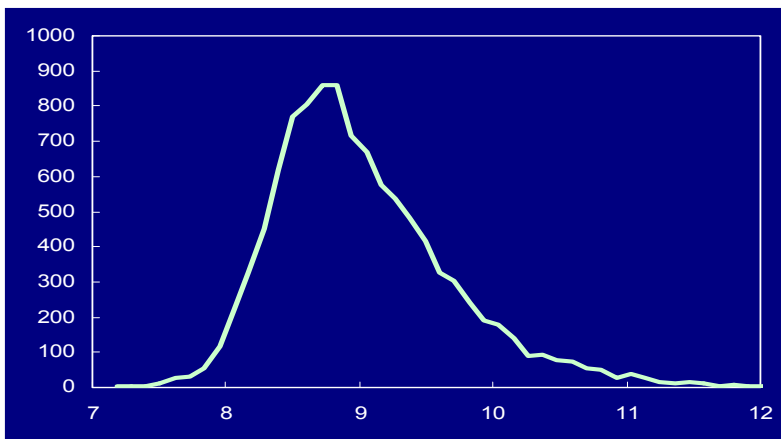
- Database of many hi-res structures (~100, 2 Å)
- Volumes statistics for buried residues (various selections, resample, &c)
- Standard atomic volumes harder... parameter set development...

G 64	c 105	T 120	V 139	H 159	M 168	R 194
A 90	C 113	P 124	E 140	L 165	K 170	Y 198
S 94	D 117	N 128	N 150	I 165	F 193	W 233

Standard Core Volumes (Prelim.)

Atom Types		Num.	Volume (Å ³)	Error (%)
Mainchain Atoms				
carbonyl carbon (except G)	C	8361	9.2	.08
alpha carbon (except G)	CA	7686	13.4	.09
nitrogen (except P)	N	9042	13.9	.09
carbonyl oxygen	O	7831	15.8	.10
Gly C		811	10.2	.27
Gly CA		522	23.5	.39
Pro N		334	8.6	.39
Sidechain atoms				
trigonal or aromatic carbon	>C=	3026	10.3	.13
aromatic CH (H,F,W,Y)	-CH=	4333	21.1	.14
aliphatic CH	>CH-	3411	14.6	.14
methylene group	-CH2-	5427	23.7	.12
methyl group (A,V,L,I)	-CH3	5273	36.7	.11
hydroxyl oxygen (S,T)	-OH	851	17.2	.36
carbonyl oxygen (N,Q)	=O	272	16.8	.76
carboxyl oxygen (D,E)	-O	517	16.0	.53
2° amine (R,H,W)	-NH-	530	15.6	.53
1° amine or amide (R,N,Q)	-NH2	355	23.4	.52
tetrahedral nitrogen (K)	-NH3	31	20.0	1.40
thioether or disulfide (C,M)	-S-	1242	19.3	1.22
sulfhydryl (C)	-SH	67	37.8	1.33

Histogram Analysis of the C3H0s

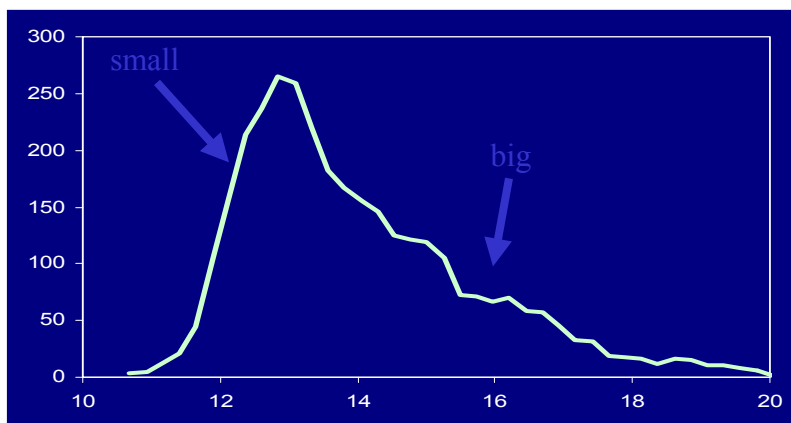


Volume

Courtesy of N Voss

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Histogram Analysis of the N3H1



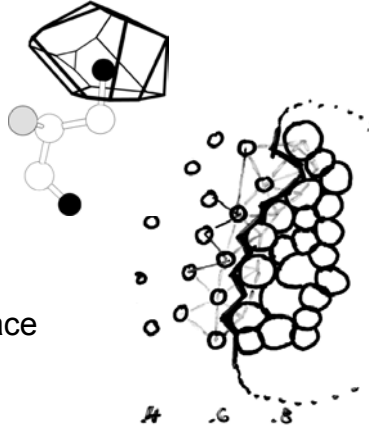
Volume

Courtesy of N Voss

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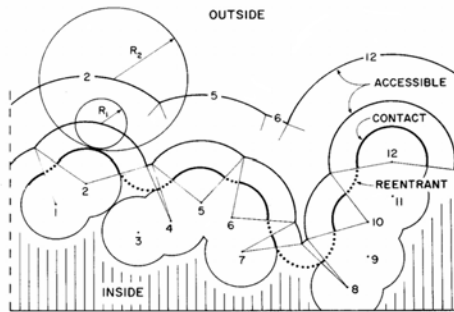
Packing at Interfaces

- Voronoi volumes (and D. triangulation) to measure packing
- Tight core packing v. Loose surface packing
- Grooves & ridges: close-packing v. H-bonding
- How packing defines a surface (hydration surface)
- Implications for Motions



Richards' Molecular and Accessible Surfaces

Core

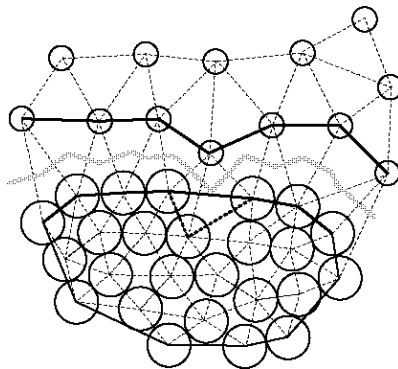


Probe Radius	Part of Probe Sphere	Type of Surface
0	Center (or Tangent)	Van der Waals Surface (vdWS)
1.4 Å	Center	Solvent Accessible Surface (SAS)
""	Tangent (1 atom)	Contact Surface (CS, from parts of atoms)
""	Tangent (2 or 3 atoms)	Reentrant Surface (RS, from parts of Probe)
""	Tangent (1,2, or 3 atoms)	Molecular Surface (MS = CS + RS)
10 Å	Center	A Ligand or Reagent Accessible Surface
∞	Tangent	Minimum limit of MS (related to convex hull)
""	Center	Undefined

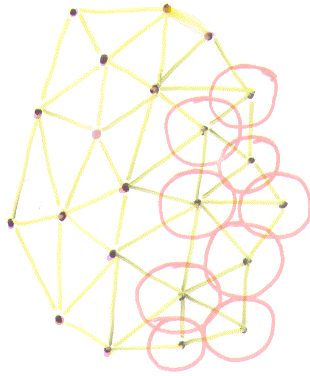
Packing defines the “Correct Definition” of the Protein Surface

- Voronoi polyhedra are the *Natural* way to study packing!
- How reasonable is a geometric definition of the surface in light of what we know about packing
- The relationship between
 - ◇ accessible surface
 - ◇ molecular surface
 - ◇ Delauney Triangulation (Convex Hull)
 - ◇ polyhedra faces
 - ◇ hydration surface

Surface and Volume Definitions Linked



Defining Surfaces from Packing: Convex Hull and Layers of Waters



Water

Protein

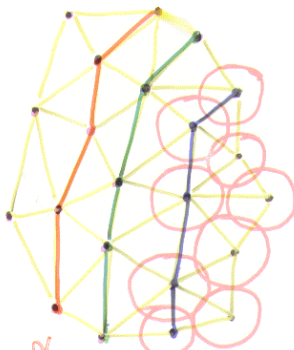


Water

Protein

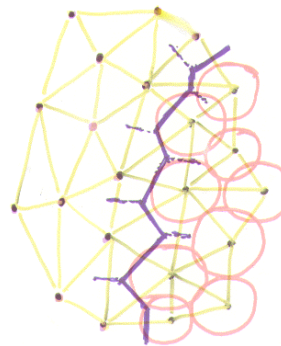
83 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Defining a Surface from the Faces of Voronoi Polyhedra



Water

Protein

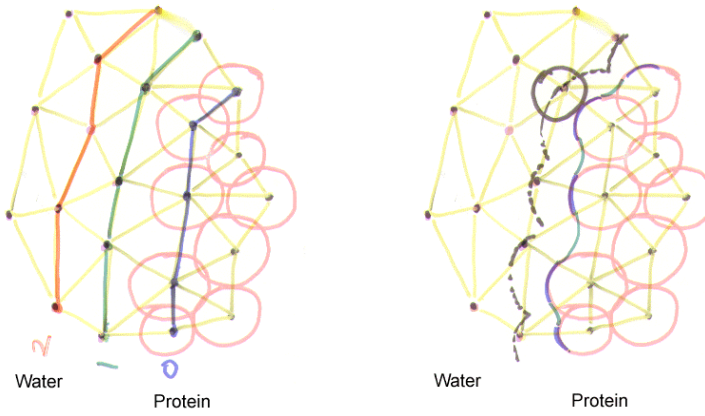


Water

Protein

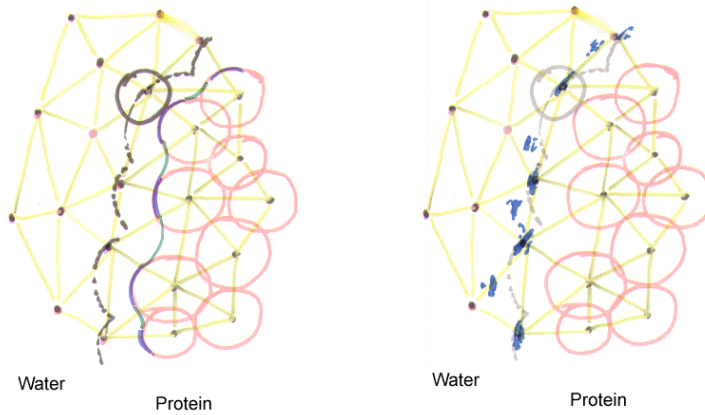
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Accessible Surface as a Time-averaged Water Layer



85 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

The Hydration Surface: Trying to Model Real Water



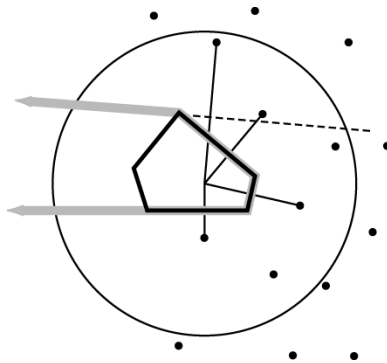
86 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Surfaces

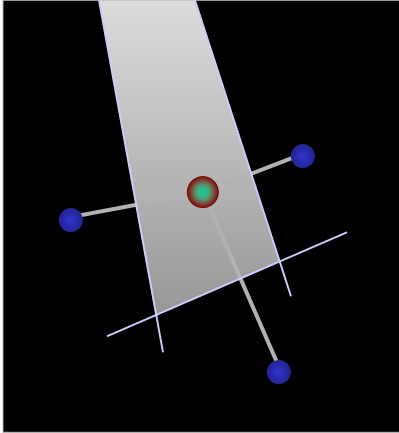
(slides 1-10, 20-40 from website)

These are detailed slides on how to do
Voronoi construction.
Go to <http://bioinfo.mbb.yale.edu/geometry>
and follow links to “HyperTalk” tutorial on
surfaces and volumes

Problem of Protein Surface for Voronoi Construction



Problems with Voronoi Volumes



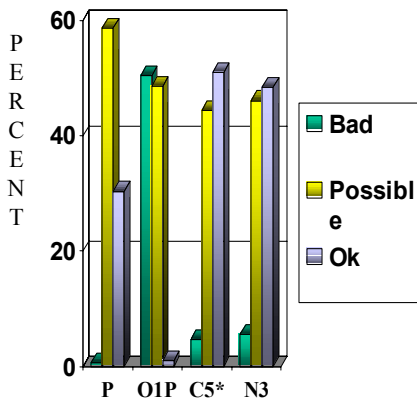
- When the Atoms are located on the Surface the Voronoi Volume fails

Ways to Correct for Unclosed Volumes

- Obtain Asymmetric Crystal Packing
- Adjust for Atom Size

Courtesy of N Voss

Quality of Measurement

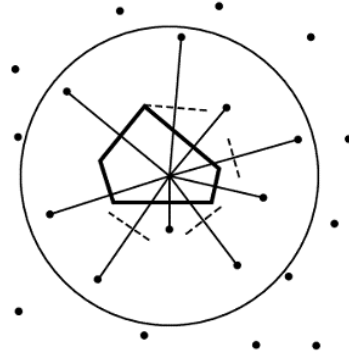


- Determine Quality By Surface Area
- If Surface Falls Below Certain Value Classified as "Ok"

Courtesy of N Voss

Voronoi Volumes

- Each atom surrounded by a single convex polyhedron and allocated space within it
 - ◇ Allocation of all space (large V implies cavities)
- 2 methods of determination
 - ◇ Find planes separating atoms, intersection of these is polyhedron
 - ◇ Locate vertices, which are equidistant from 4 atoms



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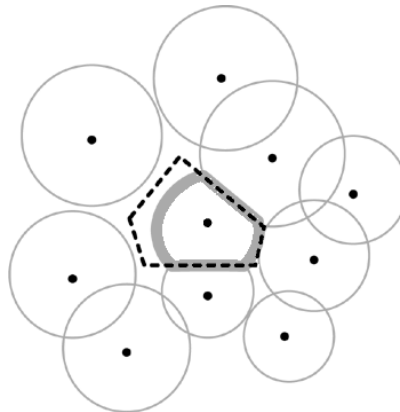
Voronoi Volumes, the Natural Way to Measure Packing

Packing Efficiency

$$= \frac{\text{Volume-of-Object}}{\text{Space-it-occupies}}$$

$$= \frac{V(\text{VDW})}{V(\text{Voronoi})}$$

- Absolute v relative eff.
 $V1 / V2$
- Other methods
 - ◇ Measure Cavity Volume (grids, constructions, &c)

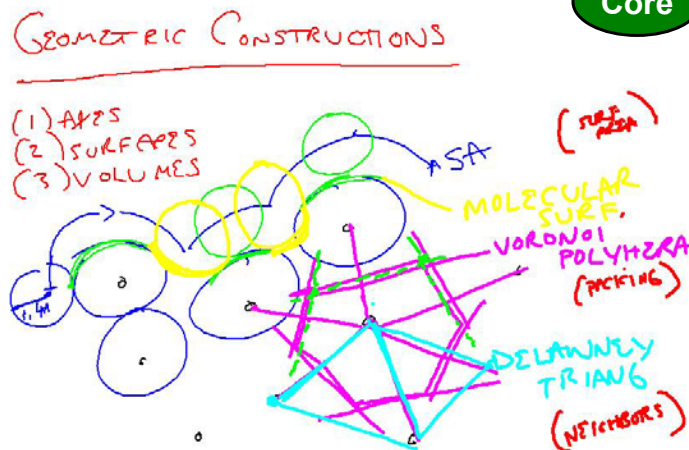


92 (c) Mark Gerstein, 1999, Yale, bioinfo.mbb.yale.edu

Calculating Volumes with Voronoi polyhedra

- In 1908 Voronoi found a way of partitioning all space amongst a collection of points using specially constructed polyhedra. Here we refer to a collection of "atom centers" rather than "points."
- In 3D, each atom is surrounded by a unique limiting polyhedron such that all points within an atom's polyhedron are closer to this atom than all other atoms.
- Likewise, points equidistant from 2 atoms form planes (lines in 2D). Those equidistant from 3 atoms form lines, and those equidistant from 4 centers form vertices.

Summary of Geometric Constructions



End of class 2002,11.13
(Bioinfo-10)
[Next is discussion of
expression]