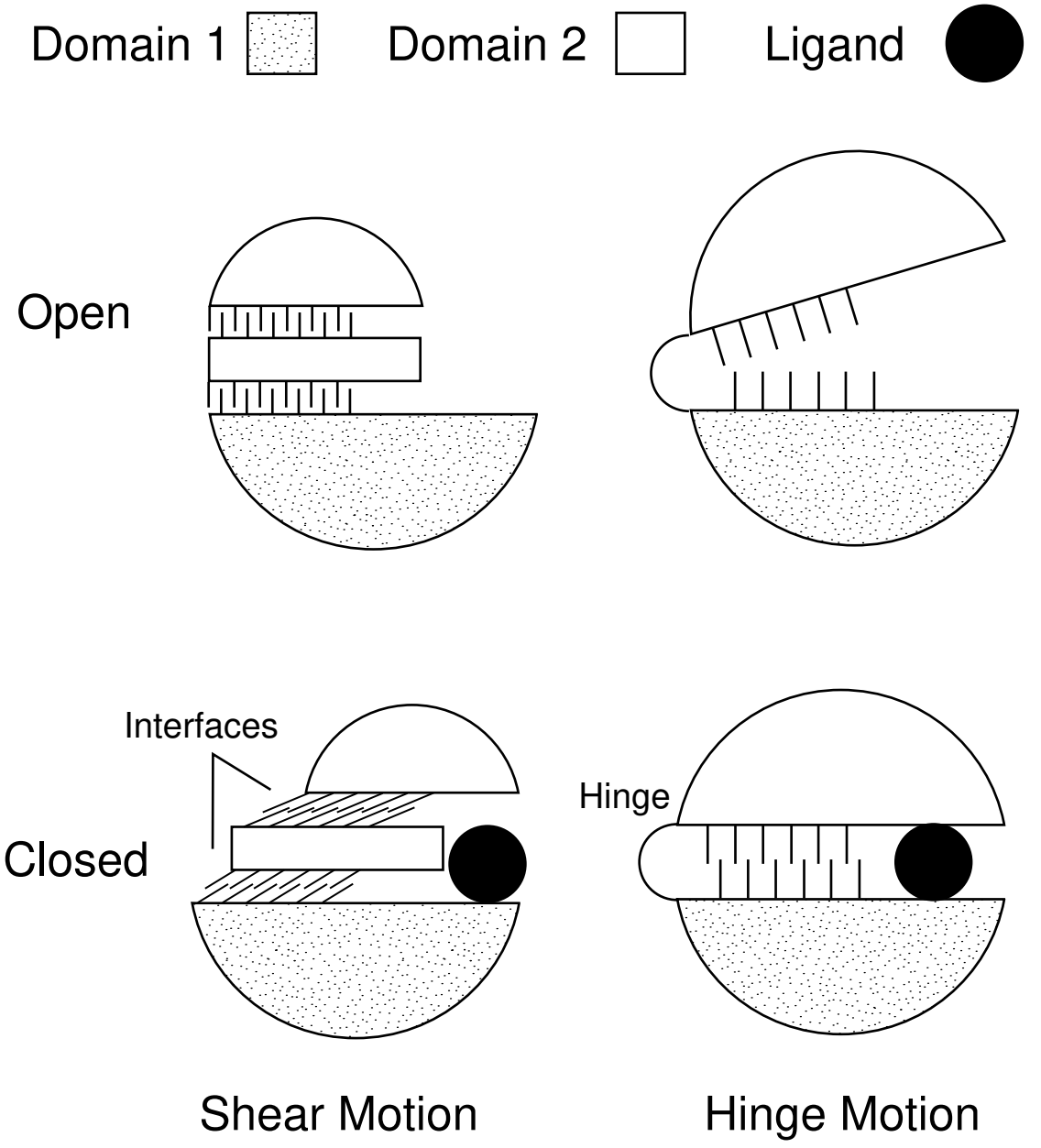
Domain 1
Domain 2
Ligand
Open
Interfaces
Closed
Hinge
Shear Motion
Hinge Motion

Fig 1